





### Results from the Commissioning of the ATLAS Pixel Detector with (and without) Cosmics Data

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# Outline

- Introduction to the ATLAS Pixel Detector
- Results from the calibration periods
  - the way to data-taking: detector response
    - threshold, ToT, charge calibration, quality studies
  - cosmic ray data-taking results
    - alignment, efficiencies, depletion depth, Lorentz angle
- Readiness of the Pixel Detector and perspective

# The ATLAS Experiment

- Largest multipurpose particle detector at CERN
- Employs a 3component inner tracking system
  - the Pixel Detector is the innermost part



# The Pixel Detector

430mm

- Requirements
  - resolution in rφ < 15 μm</li>
  - coverage of  $|\eta| < 2.5$
  - hit efficiency > 97%
- 3-layered silicon pixel tracker with forward disks in a 2 T solenoid field
  - I744 modules with 47,232 pixels each, resulting in ~80 million readout channels
  - innermost layer at 5 cm distance to beam pipe



### Inserted Pixel Detector



## Pixel Detector Module

#### Sensor properties

- n-in-n Si sensor with 250 μm thick pixels
- I50V bias voltage before irradiation
  - apply up to 600 V during runtime
- (normal) pixel size 50 μm x 400 μm

#### Electronics

- I6 front-end chips with bump bond connections to pixels
- each pixel is read-out using a preamplifier and a comparator with an adjustable threshold
- electronics contain a charge injection circuit which allows some calibration without data



### **Operation Periods**

- August December 2008
  - sign-off finished (foreseen in May, but delayed due to cooling plant failure)
  - calibration and cosmic ray data-taking
  - LHC injection test, but no data from Pixel Detector for safety reasons
- May July 2009
  - restart after cooling plant consolidation
  - some calibration and cosmic ray data taking
- August 2009 now
  - new detector calibration and recovery of bad modules
  - started cosmic ray data taking until LHC start

### Threshold

#### Threshold has to be tuned

- need good signal/background
- need to have high hit efficiency for charged particles
- Threshold tuned to be 4,000 e<sup>-</sup>
  - a MIP deposits ~20,000 e<sup>-</sup> in the sensor
  - dispersion ~40 e<sup>-</sup> (note the logscale)



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  - threshold/noise ~25
    with noise ~170 e<sup>-</sup>



# Time over Threshold

- The comparator translates the preamplifier output into a time over threshold (ToT) information
  - the shape of the signal at the comparator is altered by changing the feedback current
  - a signal length of 30 bunchcrossings (BC) at a deposited charge of 20,000 e<sup>-</sup> is targeted
    - I BC = 25 ns
  - uniform response after tuning



# ToT Calibration

- Dependance of ToT measured by varying the injected charge
  - approximately linear, confirms expected behavior
  - biased spreads at high injected charges (but note the logarithmic scale)
  - this measurement does not correspond to a physics requirement of the Pixel Detector (energy loss)



# Monitoring of the Sensor Status

- Quantities that change with radiation damage have been assessed
  - the residual leakage current through the sensor will rise over time
  - at this point, the leakage current for most pixel is below the measurement accuracy of 125 pA
    - this also adds to the noise



# Cosmic Ray Data Taking

- During the run periods in 2008 and 2009 a total of 700,000 tracks was collected
  - 310,000 tracks with magnetic field



# **Example Track**

#### Event display with reconstructed track

- magnetic field off
- 8 pixel hits are registered, the additional hits are due to overlapping modules
- displayed red are hits on track, green are noise hits
  - one noise hit in the Pixel Detector



# Example Track

- Another event display with reconstructed track
  - magnetic field on
  - TRT hits are also visible
  - no noise hits in the Pixel Detector



### Noise and Masked Pixels

Dedicated random trigger runs are taken to collect "noise data"

- a noise mask is generated from this data
- pixels with a hit occupancy exceeding a threshold are masked from data-taking



#### Noise and Masked Pixels



# **ToT Resolution**

- The detector response was simulated with a MIP deposition of 19,000 e<sup>-</sup>
  - The data shows a Landau peak at 18,700 e<sup>-</sup>
- This verifies the ToT - charge calibration



# Alignment

• Alignment can spot mechanical features of the detector



# Alignment

Effect of alignment on residuals

- clear proof of principle for alignment algorithms
- residuals in precision direction ~24 μm



# Efficiencies

- Efficiency for attaching of hits to tracks
  (for the barrel)
  - well above 99.5%, therefore exceeding the requirement of 97%
  - after masking noisy pixels
  - disabled modules are not considered



# Timing

- The Pixel Detector has to be synchronous with the ATLAS clock
  - for cosmic ray data-taking, more than one BC is read out per trigger
  - the timing of the modules was calibrated to have a hit in BC 3 after the trigger, for signal events
  - main effects like cable lengths are corrected, remaining effects are, for example, signal shape details like the "timewalk"
  - start with 5 BC readout and reduce to I BC later



# **Depletion Depth Measurement**

- Tracks can be used for different studies of sensor related quantities
  - the track depth in the last pixel of a hit cluster can be used to calculate the depletion depth of the module
  - result: (251.2 ± 9.5) μm
    - good agreement with the sensor thickness of ~250 μm
  - the depletion depth can be monitored while radiation damage increases



# Lorentz Angle Measurement

- The charge collection path in the sensor is altered by the solenoid field
  - the Lorentz angle is the effective correction on the particle track compared to the no B-field case
  - measured with cluster size vs. track incidence angle
  - 225 mrad expected, good agreement



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  - decrease of Lorentz angle with temperature also in good agreement with expectation (-0.74 mrad/K)



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#### Detector "evolves"

- during the commissioning, problematic modules have to be disabled from data-taking
- recovering and re-integrating them is a main focus of the commissioning periods



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- recovering and re-integrating them is a main focus of the commissioning periods
- improved understanding of the detector leads to a high fraction of usable modules in the current state
  - more modules operable since June 2009: 98% currently operable



### **Current Status and Perspective**

#### • 98% of the pixel detector are usable for data-taking

- threshold tuning and charge calibration are well understood, threshold is at 4000 e<sup>-</sup> and noise is ~170 e<sup>-</sup> with a threshold/noise of ~25, noise occupancy is at ~10<sup>-10</sup> hits/pixel/BC
- already good timing will allow a quick reduction of the readout window
- hit efficiency is well above 99.5% and residuals  $\sim$ 24  $\mu$ m in precision direction

#### Plans

- tuning at low thresholds is being investigated for future operation phase and for beam pickup studies
- cosmic ray data taking will continue

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#### The Pixel Detector is ready for the LHC startup and for first data!

# Backup

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### Track Collection Rate



# **Threshold Principle**



# **Different Pixel Types**



# Lorentz Angle



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# **Depletion Depth Principle**



### Pixel Cell

