

An overview of the ITER interlock and safety systems

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Outline

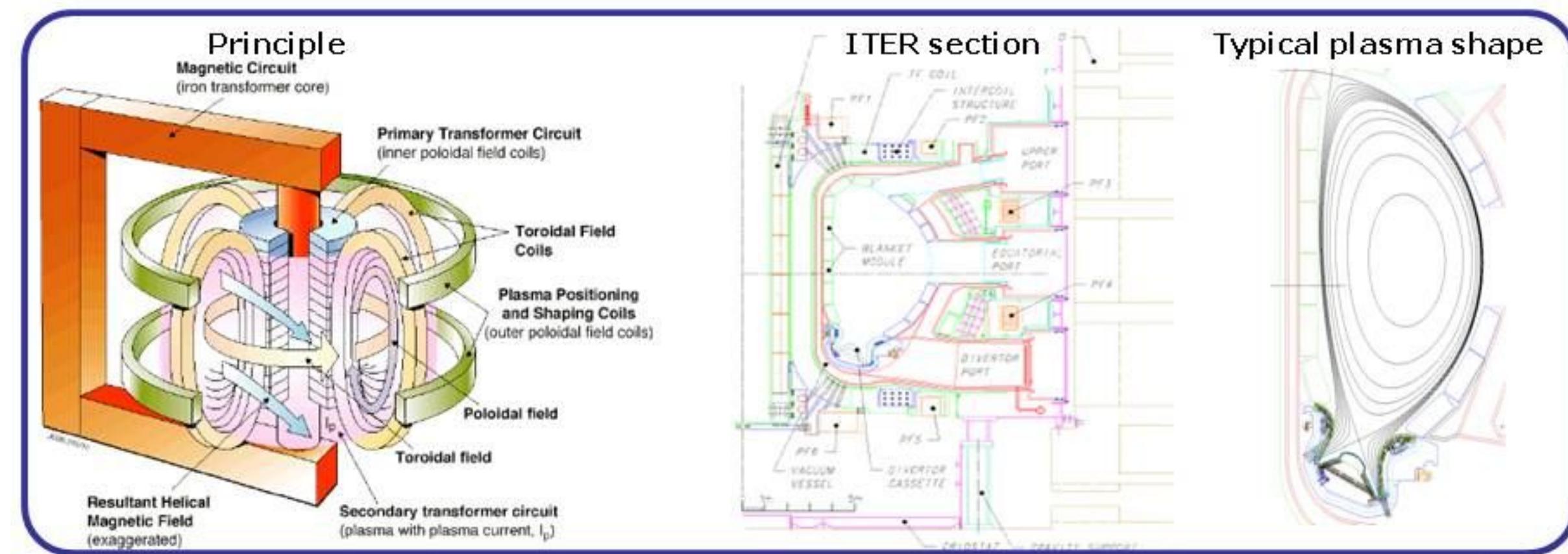
- Context of the interlock and safety systems in ITER
- Main functional requirements
- Main design requirements
- Main system requirements
- Some current activities

Context of the interlock and safety systems in ITER

- Origin of the requirements:**
 - ITER involves a number of potential identified hazards to personnel, the environment, and to the machine itself: the main hazards being linked to radiations, the stored energies, the operation of the large industrial systems and the operation of the plasma
 - ITER Generic Site Safety Report (GSSR)
 - Preliminary Safety Report (Rapport Préliminaire de Sûreté, RPrS)
- The regulatory context**
 - ITER is classified as Basic Nuclear Installation (Installation Nucléaire de Base, INB) based on the French Laws
- The procurement structure and the technical organization**

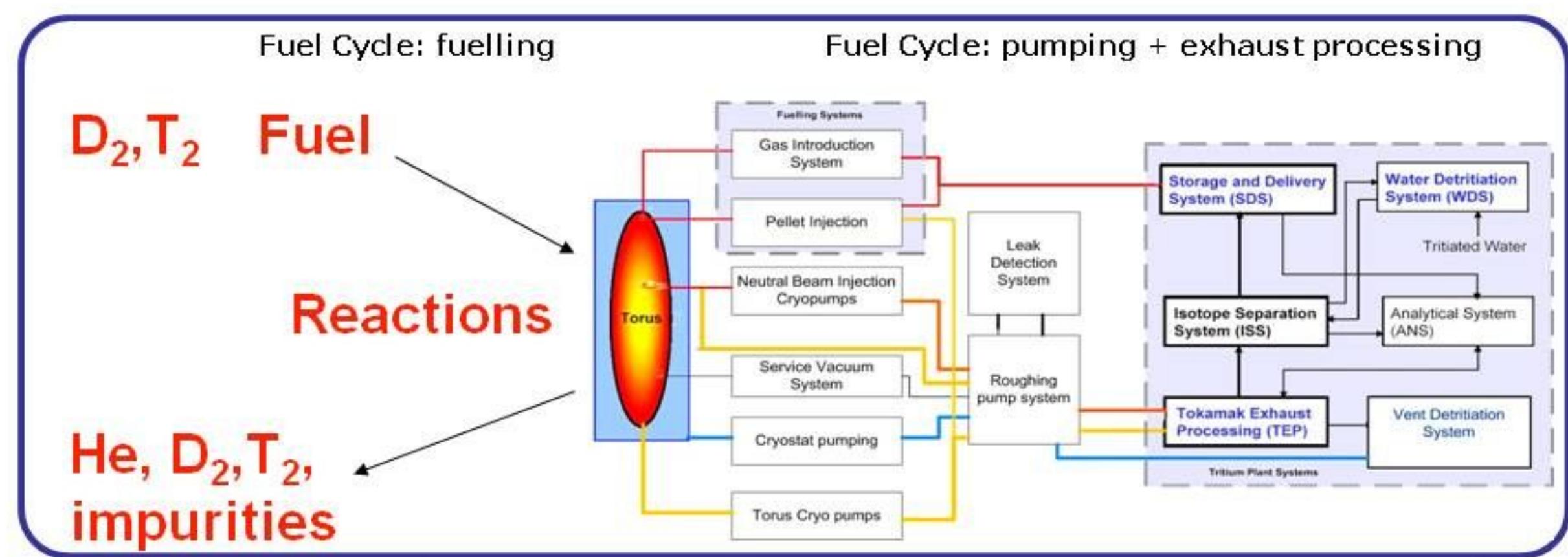
Why protections: examples (1/2)

- Tokamaks work on the principle of magnetic confinement:
 - Creating a magnetic “bottle” giving a shape to the plasma and keeping it isolated from the physical container (Vessel).
 - magnetic bottle depends on the current flowing in the superconducting coils and the plasma current in a very delicate equilibrium.
- Superconducting magnets:
 - High stored energy $\sim 100\text{GJ}$ -> Quench, plasma termination
 - Interaction of strong magnetic fields ($\sim 5\text{T}$, up to $\sim 17\text{MA}$) -> power interlock, coil protection, disruption mitigation.

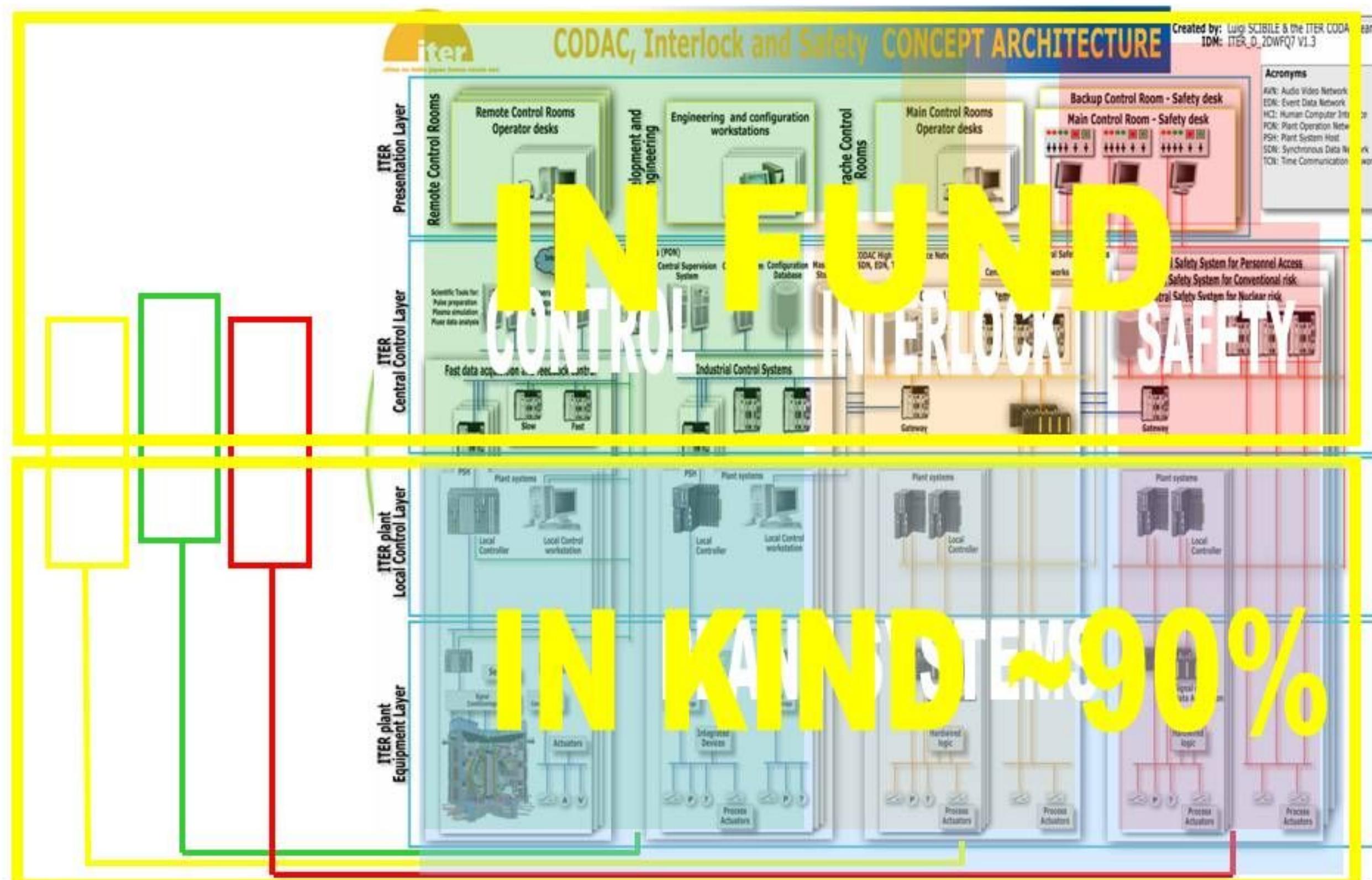


Why protections: examples (2/2)

- In Tokamaks, the fusion elements and products can be radioactive:
 - One of the fusion reaction is based on Deuterium-Tritium elements (to generate 500 MW of total fusion power, about 0.4 g of tritium will be burnt)
 - However, the operational conditions require that more than 100 g of tritium will be injected into, pumped from the vessel and processed on line
- Confinement:
 - Leakages -> Confinement components protection, Isolation valves and buffer circuits
 - Human actions -> interlock risky operations.



Two layers - Three tiers



Main functional requirements

- The main functions are linked to:
 - the confinement of the radioactive material
 - the limitation of internal and external exposure to ionizing radiations
 - the stored energies
 - the operation of the large industrial systems
 - the operation of the plasma
- Grouped in two main categories:
 - Protection functions
 - Monitoring functions.
- Functional analysis:
 - To map the functional requirements to actual plant systems
 - To identify and formalize the interfaces between the various plant systems and the central systems.

Main design requirements

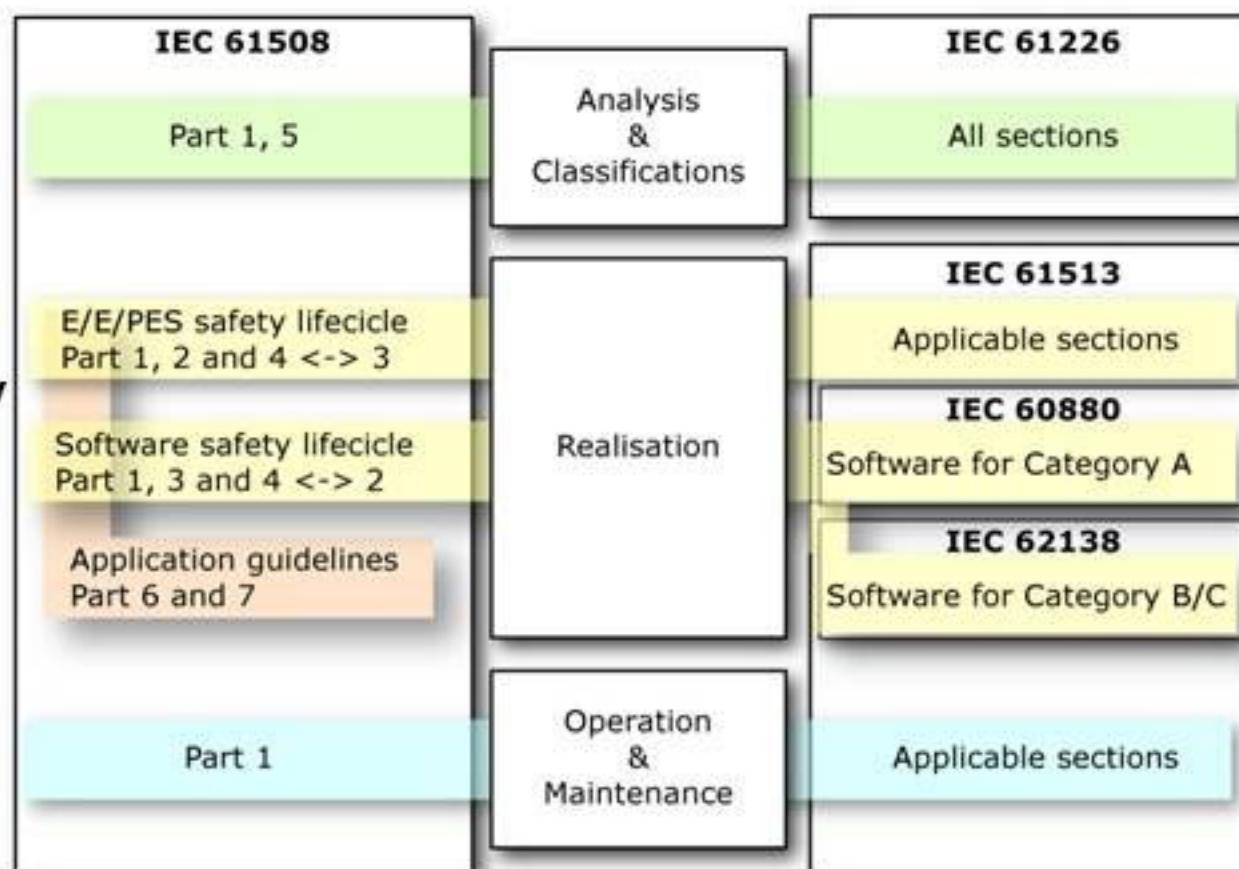
- Top level design principles:
 - Graded approach
 - Defense-in-Depth principles and separation
 - Redundancy and Single Failure Criteria
 - Avoidance of Hazards
 - Priority among the 3 tiers
- Based on:
 - The current ITER design and organized in the ITER Plant Control Design Handbook
 - Recommendations and requirements from selected standards

Application of international standards

- IEC 61508 Family: to minimize diversity in the development approach
- To unify the communication in terms of common objectives
- For the compliance to the national regulations that are in vigour in France where ITER is located

For conventional instrumented safety systems:

[IEC 61508], Functional safety of E/E/PES safety related systems



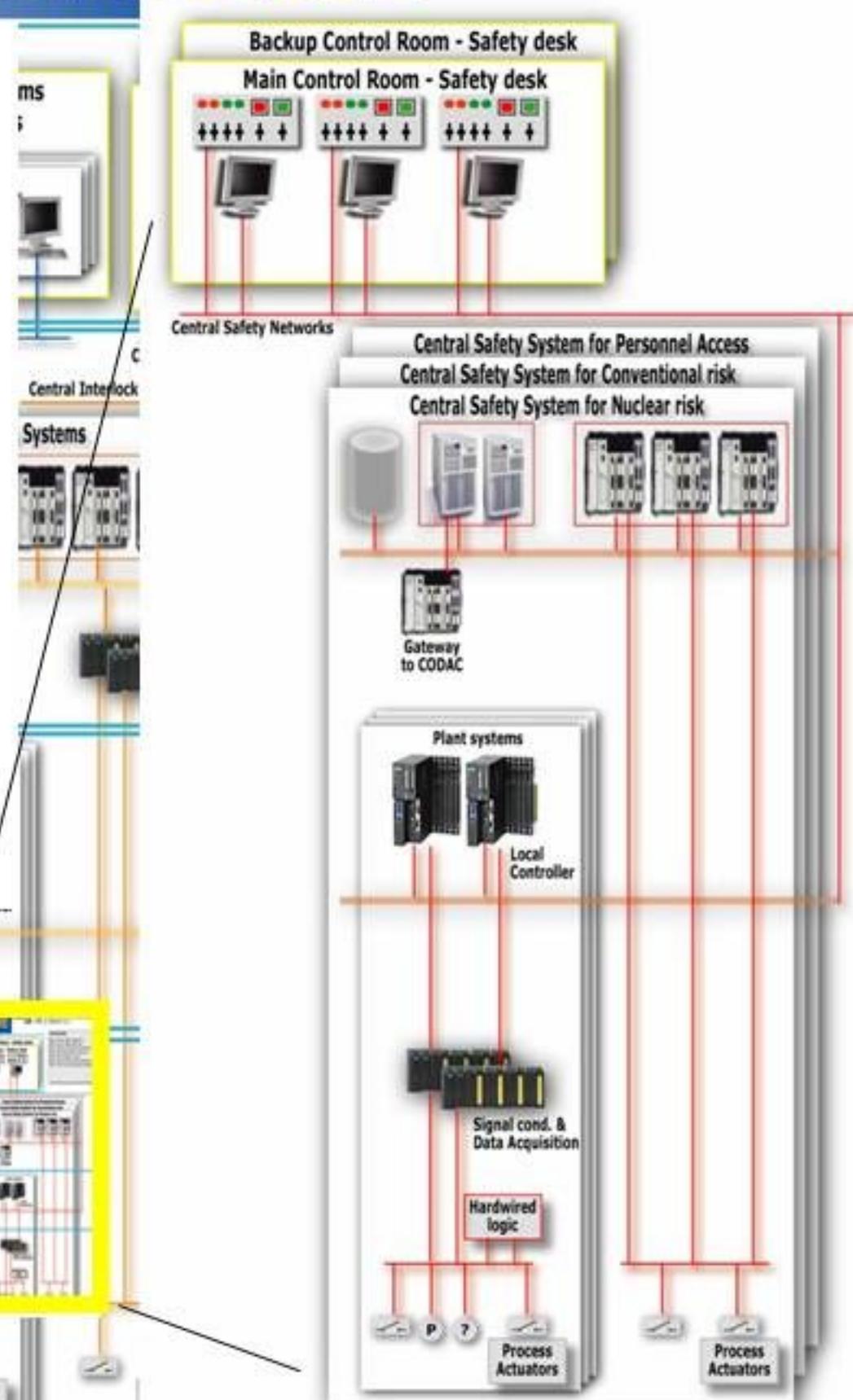
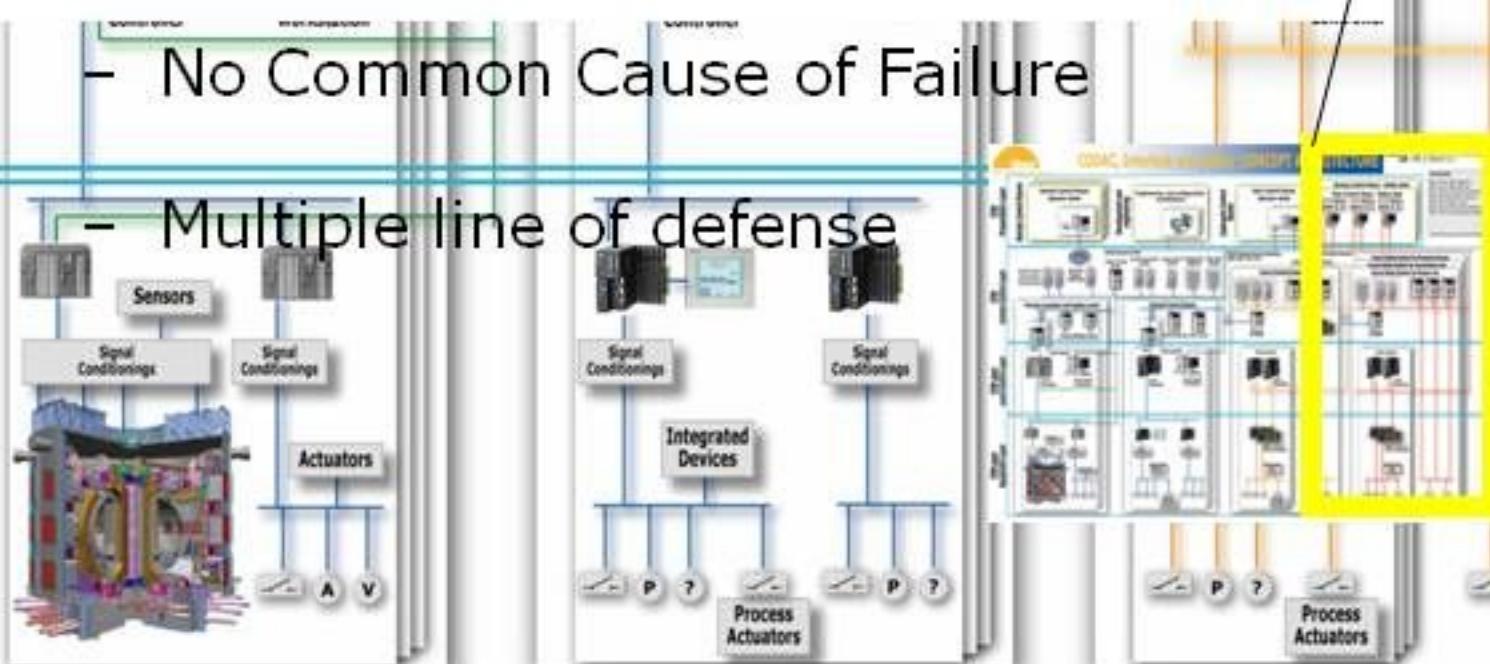
For the nuclear sector:

**[IEC 61226], Nuclear Power Plants
Instrumentation and Control Systems
Important for Safety Classification**

**[IEC 61513], Nuclear power plants
Instrumentation and control for systems important to safety
General requirements for systems**

• Main system requirements

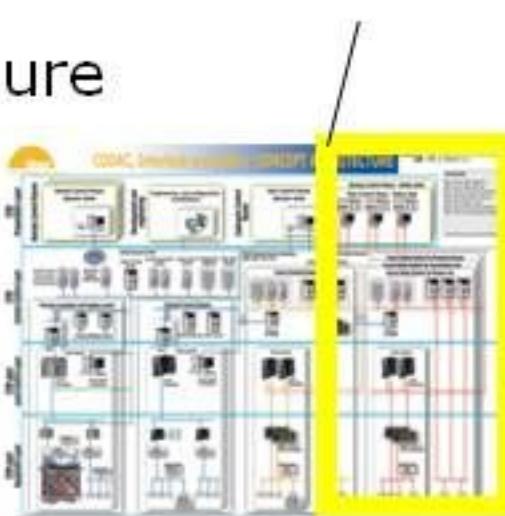
- The CSS for Nuclear risk and Personnel access are classified as a SIC system classed as implementing safety functions of category B (IEC 61226) with systems of class 2 (IEC 61513)
- Safety functions of category A will be implemented via hardwired logic with systems of class 1.



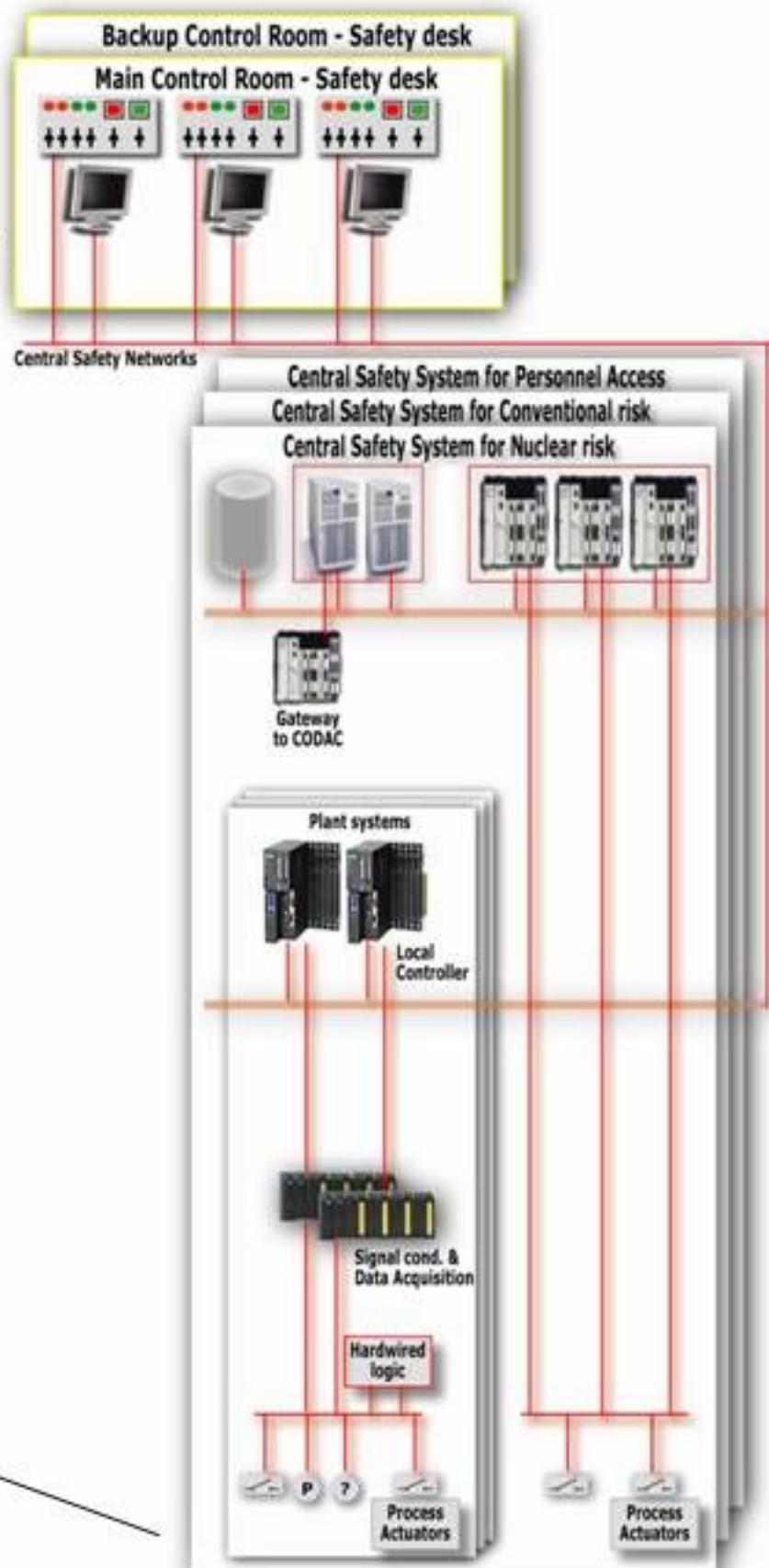
Safety Control Systems

• Main system requirements

- The CSS for Nuclear risk and Personnel access are classified as a SIC system classed as implementing safety functions of category B (IEC 61226) with systems of class 2 (IEC 61513)
- Safety functions of category A will be implemented via hardwired logic with systems of class 1.
- No Common Cause of Failure
- Multiple line of defense



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Development and engineering

Engineering and configuration workstations

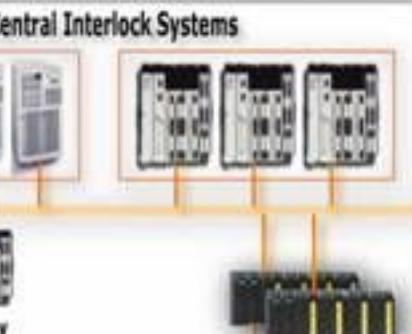
Cadarache Control Rooms

Main Op

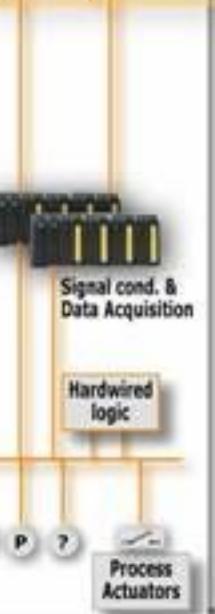
Main Control Rooms
Operator desks

CODAC Networks

Central Interlock Networks



Gateway to CODAC



Main system requirements

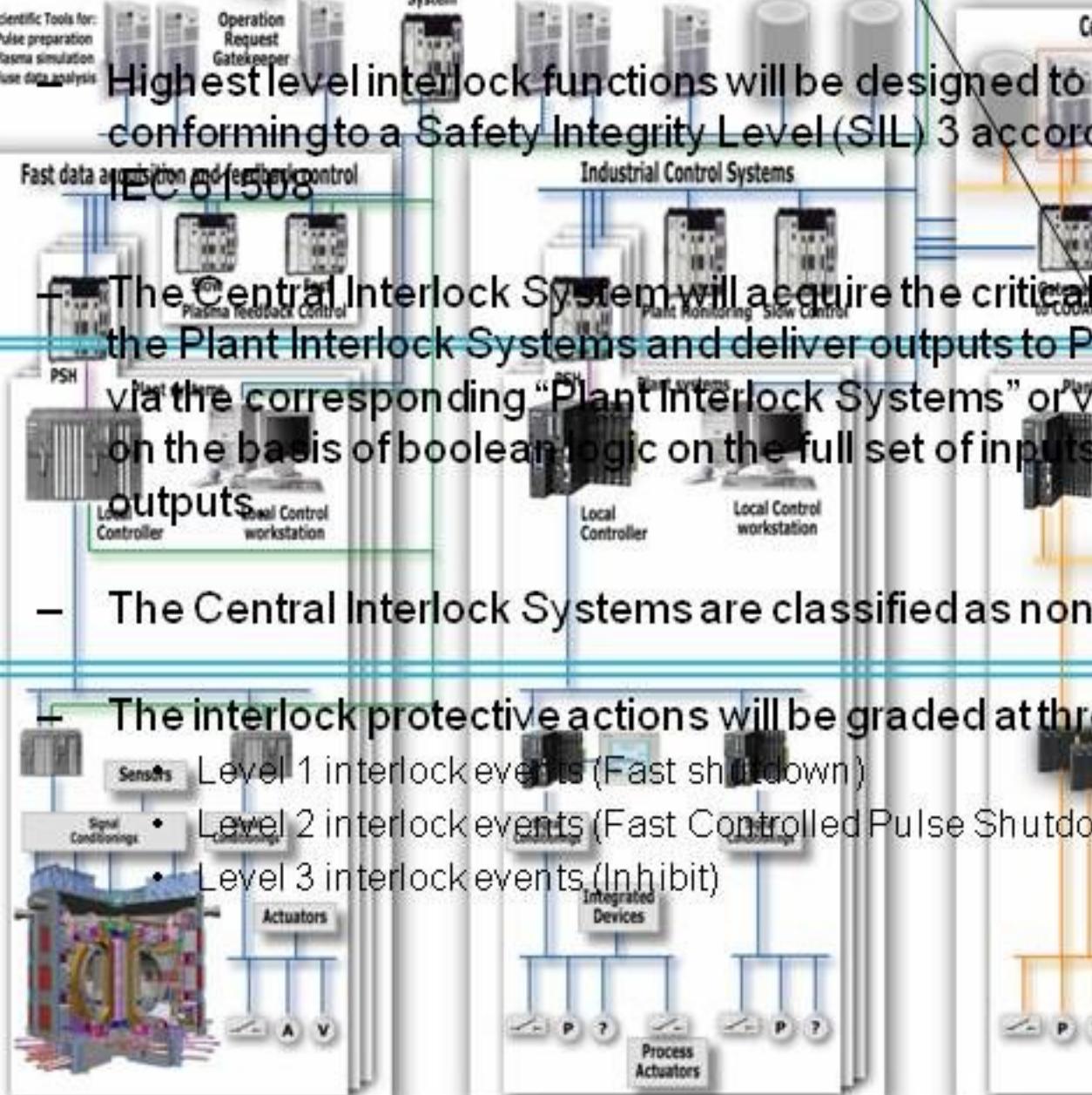
- Highest level interlock functions will be designed to a high integrity level conforming to a Safety Integrity Level (SIL) 3 according to the standard IEC 61508

- The Central Interlock System will acquire the critical digital signals from the Plant Interlock Systems and deliver outputs to Plant Systems (either via the corresponding "Plant Interlock Systems" or via direct interlocks) on the basis of boolean logic on the full set of inputs and on the latched outputs

- The Central Interlock Systems are classified as non-SIC

- The interlock protective actions will be graded at three levels:

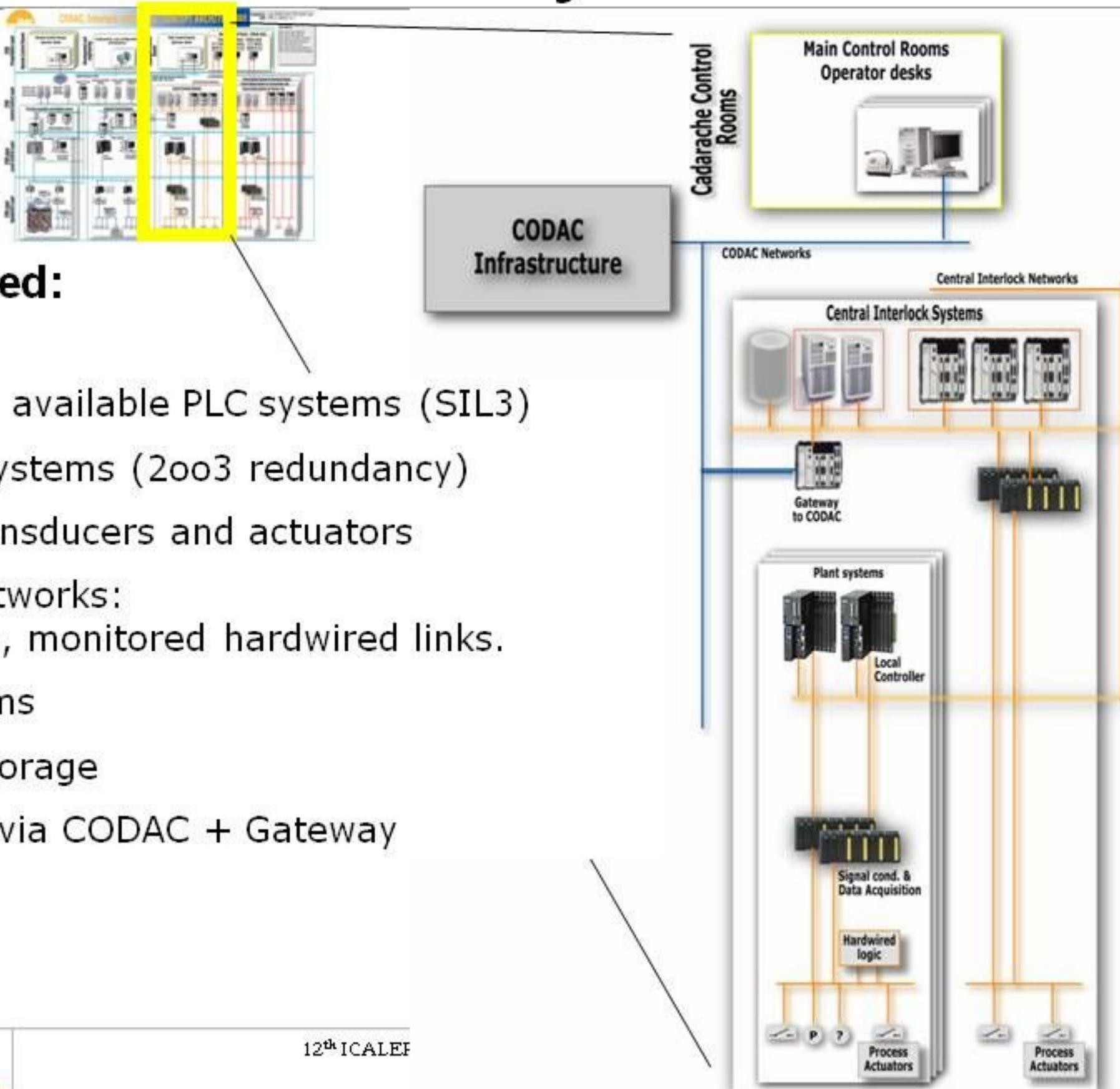
- Level 1 interlock events (Fast shutdown)
- Level 2 interlock events (Fast Controlled Pulse Shutdown)
- Level 3 interlock events (Inhibit)



Interlock Control Systems

- **Equipment required:**

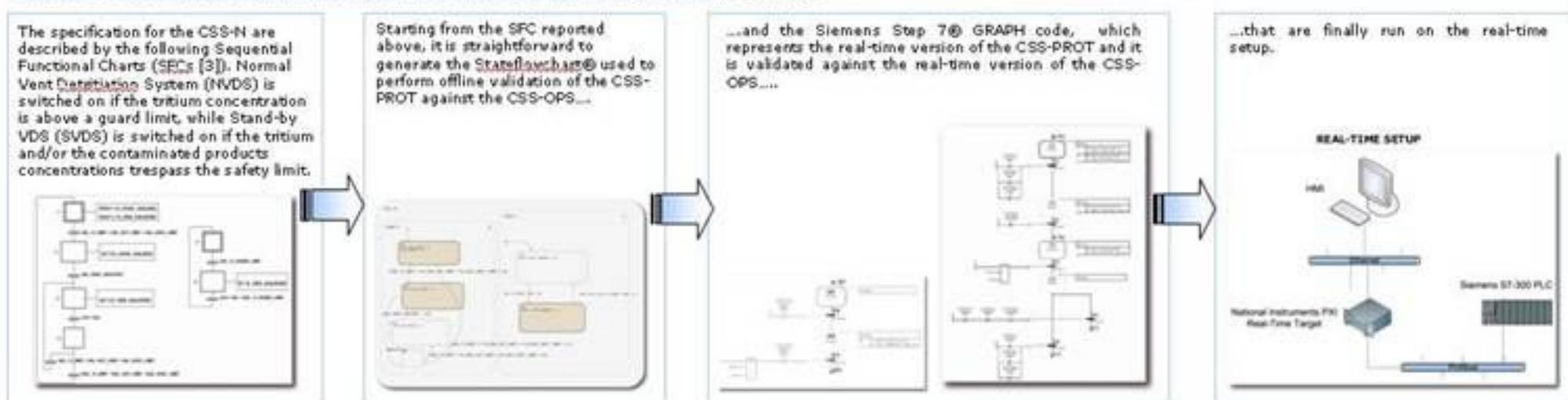
- Highly reliable and available PLC systems (SIL3)
- Some hardwired systems (2oo3 redundancy)
- Various type of transducers and actuators
- Various type of networks:
TCP/IP, field buses, monitored hardwired links.
- Supervisory systems
- Short term data storage
- Operator synoptic via CODAC + Gateway



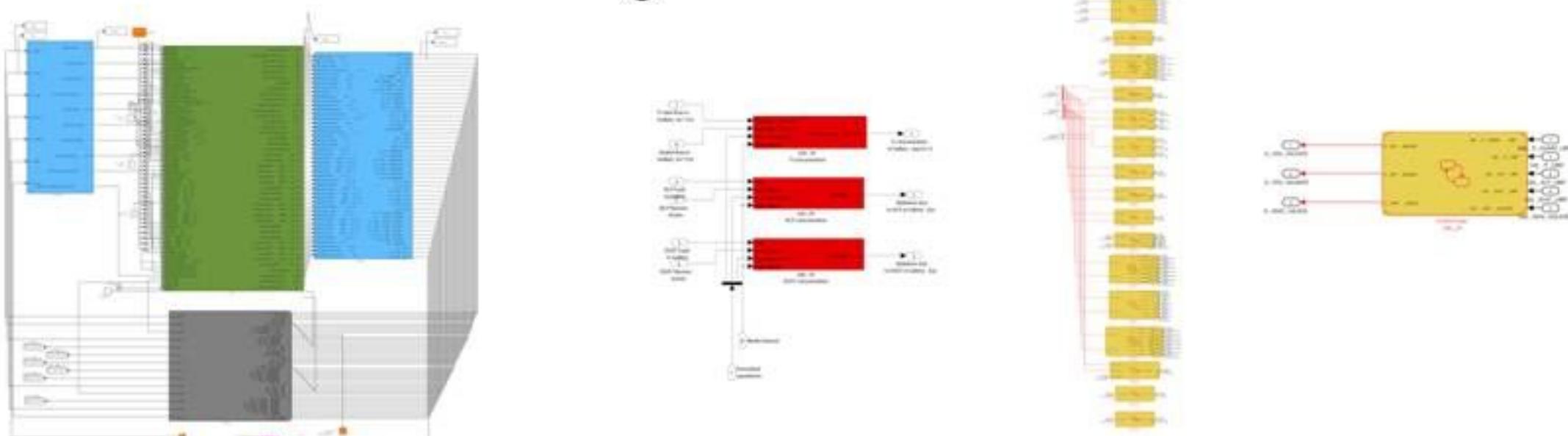
Some of the running activities (1/4)

- Documentation – writing and reviewing
- Central Safety System rapid prototype

EXAMPLE: Let consider the risk High concentration of tritium and/or contaminated products in the Gallery.



- Matlab/simulink modelling



Some of the running activities (2/4)

• Functional analysis

Function Name	Return Type	Parameters	Description	File Name	Line Number	Code Block	Annotations	Dependencies	Implementation
function1	int	(int a, int b)	Computes the sum of two integers.	src/main.cpp	10	int sum = a + b;			
function2	double	(double x, double y)	Computes the square root of the sum of two doubles.	src/main.cpp	20	double result = sqrt(x * x + y * y);			
function3	string	(string str)	Reverses the input string.	src/main.cpp	30	string reversedStr = str.reversed();			
function4	bool	(bool condition)	Returns true if the condition is met.	src/main.cpp	40	bool isTrue = condition == true;			
function5	void	(void)	Prints a message to the console.	src/main.cpp	50	cout << "Hello, World!"			
function6	int	(int a, int b)	Computes the product of two integers.	src/main.cpp	60	int product = a * b;			
function7	double	(double x, double y)	Computes the square root of the difference of two doubles.	src/main.cpp	70	double result = sqrt(x * x - y * y);			
function8	string	(string str)	Reverses the input string.	src/main.cpp	80	string reversedStr = str.reversed();			
function9	bool	(bool condition)	Returns true if the condition is met.	src/main.cpp	90	bool isTrue = condition == true;			
function10	void	(void)	Prints a message to the console.	src/main.cpp	100	cout << "Hello, World!"			
function11	int	(int a, int b)	Computes the sum of two integers.	src/main.cpp	110	int sum = a + b;			
function12	double	(double x, double y)	Computes the square root of the sum of two doubles.	src/main.cpp	120	double result = sqrt(x * x + y * y);			
function13	string	(string str)	Reverses the input string.	src/main.cpp	130	string reversedStr = str.reversed();			
function14	bool	(bool condition)	Returns true if the condition is met.	src/main.cpp	140	bool isTrue = condition == true;			
function15	void	(void)	Prints a message to the console.	src/main.cpp	150	cout << "Hello, World!"			
function16	int	(int a, int b)	Computes the product of two integers.	src/main.cpp	160	int product = a * b;			
function17	double	(double x, double y)	Computes the square root of the difference of two doubles.	src/main.cpp	170	double result = sqrt(x * x - y * y);			
function18	string	(string str)	Reverses the input string.	src/main.cpp	180	string reversedStr = str.reversed();			
function19	bool	(bool condition)	Returns true if the condition is met.	src/main.cpp	190	bool isTrue = condition == true;			
function20	void	(void)	Prints a message to the console.	src/main.cpp	200	cout << "Hello, World!"			

1-risk table

2-Functions definitions

Function definition table	
Function	Description of function (uncompleted at this time)
F51.1_G.MP.ARGP_T.LL.PR.PR	This function is a logic protection function. In PBSS1 a status detector is available on the different part of the PBSS (Line, RF source, Antenna, Matching system ...). Since its actions must be done fast AD detection but it may be difficult to know the system and the time constraints. For RF it makes difficult that can be detected at this time.

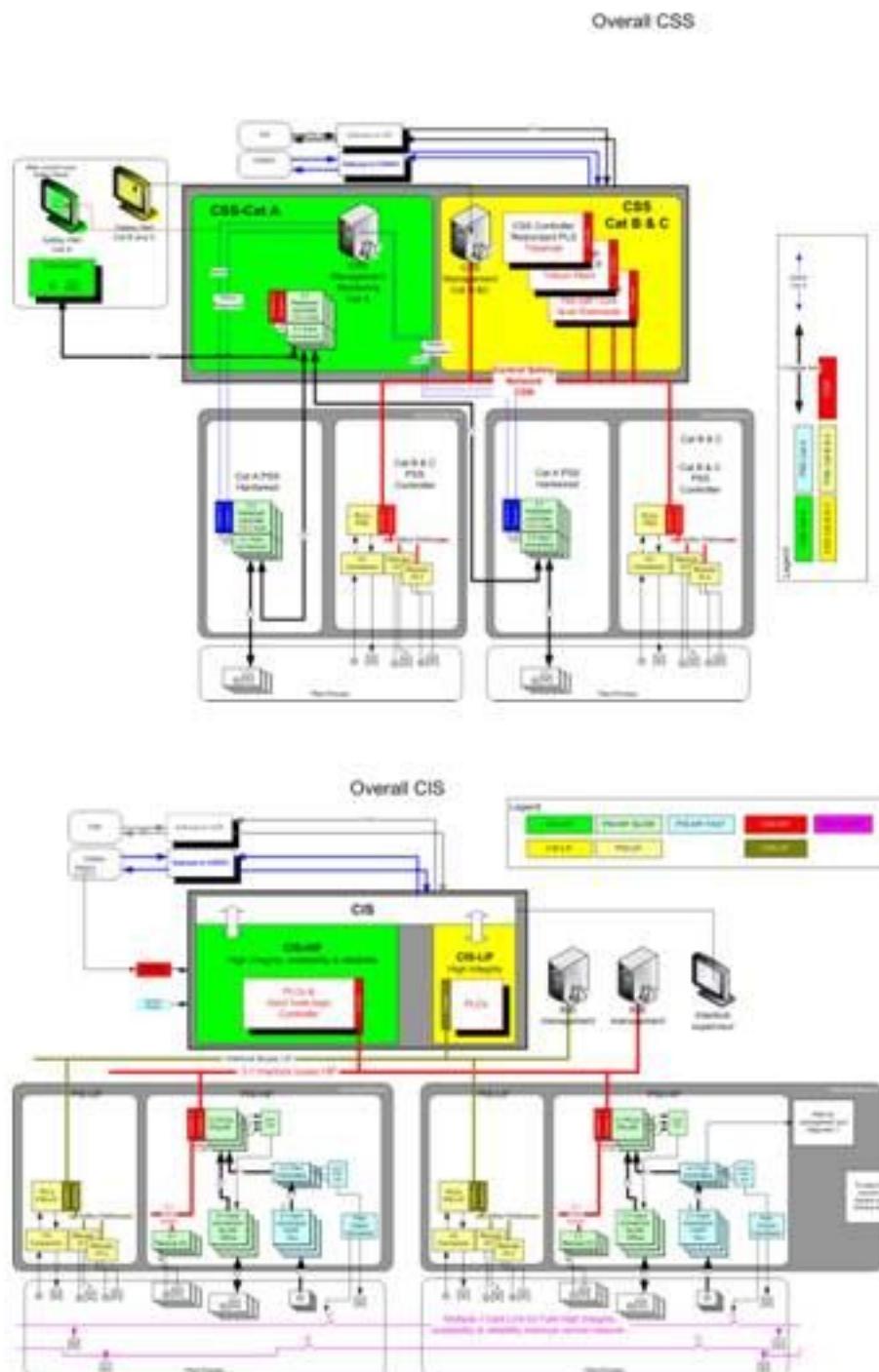
It is the job of a protection function. In PBSS1 a bitface detector is available on the different parts of the PBSS (Line, RF source, Antenna, Matching system...) define its actions in case of a deprotecting but the way to shutdown the system and the time windows are not yet defined.

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3. Functions description

Some of the running activities (3/4)

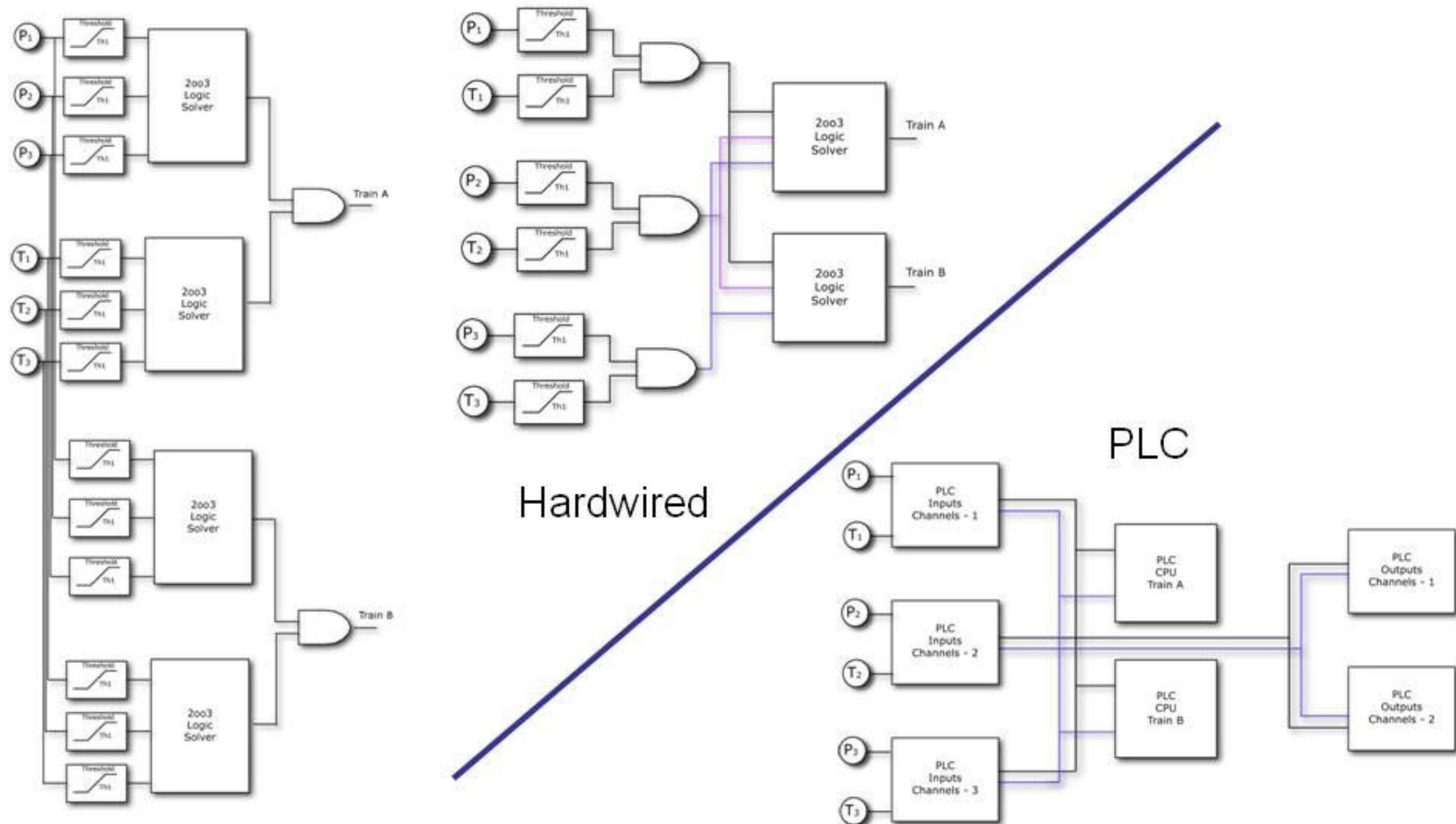
- Preliminary architectures that map the required functions



- Application of the main design requirements
- Completeness verification
- Performance Analysis of:
 - Cycle time
 - Availability – Reliability
 - Volume vs Solutions
 - Networks
- Prototype realization for
 - Performance validation
 - Preliminary safety assessment
 - Validation of architectures

Some of the running activities (4/4)

- Preliminary architectures that address the redundancies



Conclusions

- Interlock and safety control systems in ITER participate to the implementation of the general safety objective and to the overall protection of the machine.
- The Safety control systems are subject to the approval of the Nuclear French regulator
- The current main priority is on the Conceptual Design
- Some information published through our public web site:
<http://www.iter.org/org/team/chd/cid/codac/Pages/default.aspx>
- Lots of work in front of us.....

....and the target is worth the trip!

QUESTIONS?