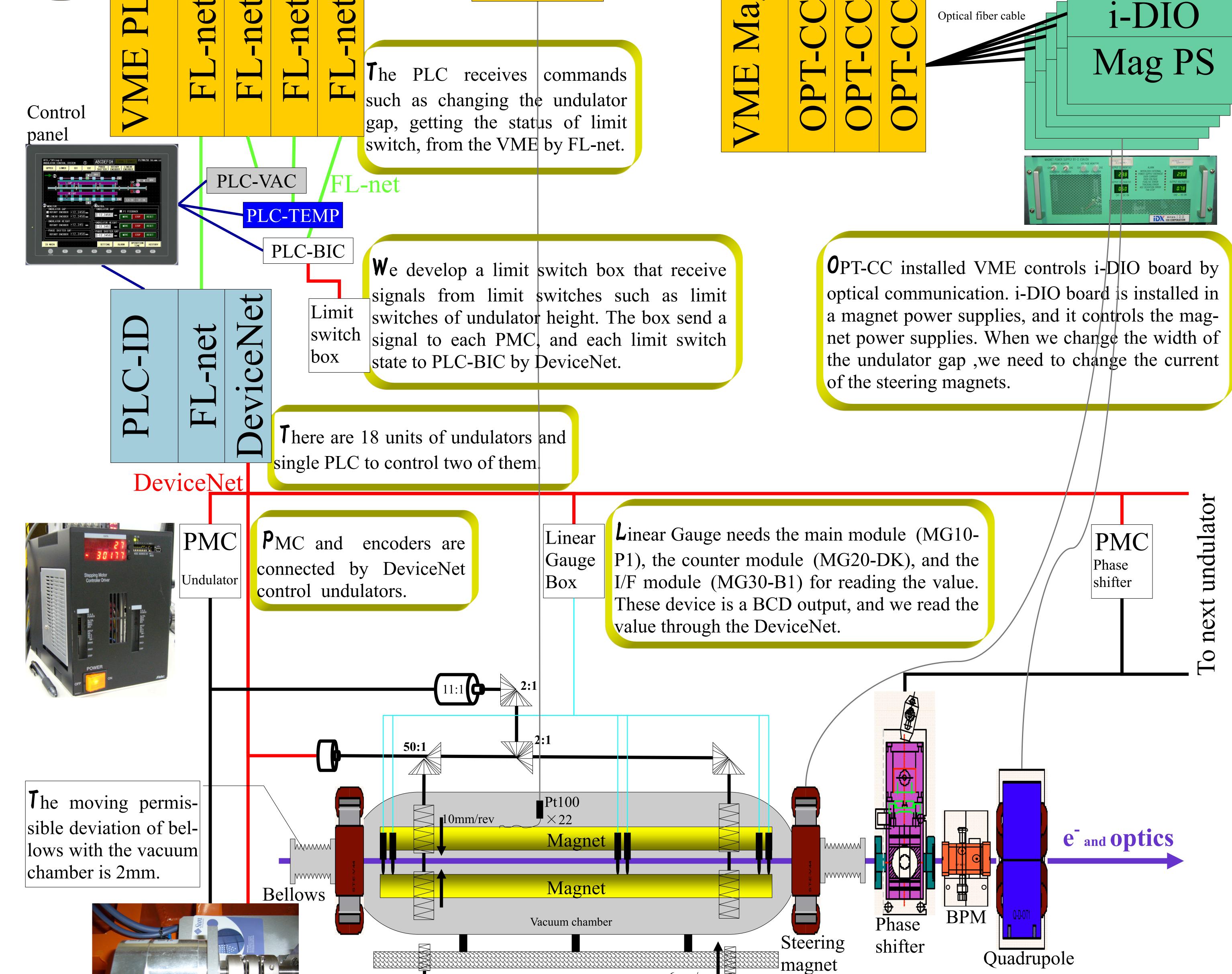
## **DEVELOPMENT OF THE UNDULATOR CONTROL SYSTEM FOR XFEL/SPRING-8** T. Otake, T. Fukui, T. Tanaka RIKEN/SPring-8 JASRI/SPring-8 T. Ohata Console We monitor the magnet array temperature by Pt100 RTD. E-069 connect to twenty-GUI four pairs of a four-terminal RTD. Temperature resolution of E-069 is $0.1^{\circ}$ C. Ethernet

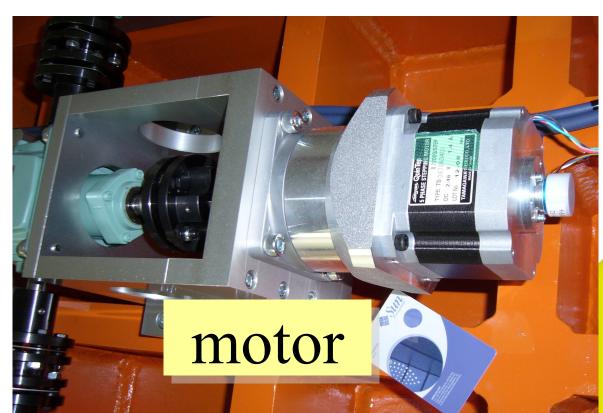
50





6mm/rev

Bevel gear ⊭



Encoder

Motor	Gap	Height
A reduction gear	2000:1	1440:1
Resolution	18 2nm/rev	8 3nm/rev

Motor

24:1

Encoder

2:1

For the lasing, we set the undulator gaps less than 1micrometer positioning accuracy. We have to control the undulator gap to be less than sub-micrometer resolution. This table shows that the resolution of these motors is sufficient.

## magnet

Undulator

without a vacuum chamber